

# Iterative Amortized Inference

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## Summary

**Iterative amortized inference models** efficiently and accurately perform variational inference optimization by iteratively encoding *approximate posterior gradients* or errors, rather than directly encoding data examples. They

- Extend amortized inference models to iterative estimation.
- Provide a principled method of explicitly including latent priors in inference optimization.
- Outperform standard inference models on image and text data sets.

## Background

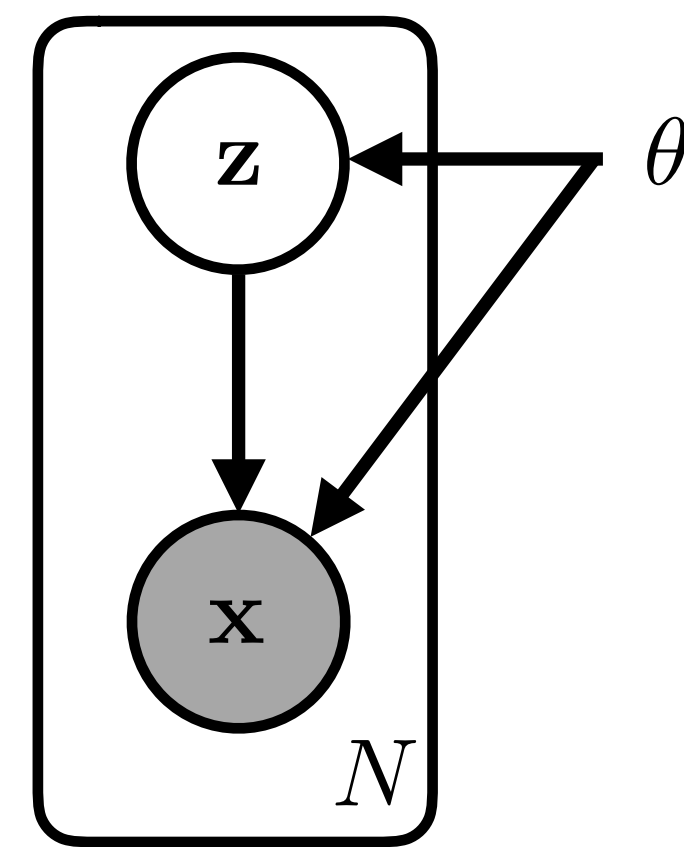
### Latent Variable Model

$$p_{\theta}(\mathbf{x}, \mathbf{z}) = p_{\theta}(\mathbf{x}|\mathbf{z})p_{\theta}(\mathbf{z})$$

### Latent Gaussian Model

Prior  $p_{\theta}(\mathbf{z}) = \mathcal{N}(\mathbf{z}; \mu_p, \sigma_p^2)$

Conditional Likelihood e.g.  $p_{\theta}(\mathbf{x}|\mathbf{z}) = \mathcal{N}(\mathbf{x}; \mu_x, \sigma_x^2)$



### Variational Inference

Approximate Posterior e.g.  $q(\mathbf{z}|\mathbf{x}) = \mathcal{N}(\mathbf{z}; \mu_q, \sigma_q^2)$   $\lambda \equiv \{\mu_q, \sigma_q^2\}$

ELBO  $\mathcal{L} = \mathbb{E}_{q(\mathbf{z}|\mathbf{x})} [\log p_{\theta}(\mathbf{x}|\mathbf{z})] - D_{KL}(q(\mathbf{z}|\mathbf{x})||p_{\theta}(\mathbf{z})) \leq \log p_{\theta}(\mathbf{x})$

### Variational EM Algorithm [1]:

Variational **E-Step** (Inference):  $\lambda = \arg\max_{\lambda} \mathcal{L}$   
Variational **M-Step** (Learning):  $\theta = \arg\max_{\theta} \mathcal{L}$

**Conventional inference optimization**, (e.g. SVI [2]):

$$\lambda = \lambda + \alpha \nabla_{\lambda} \mathcal{L}$$

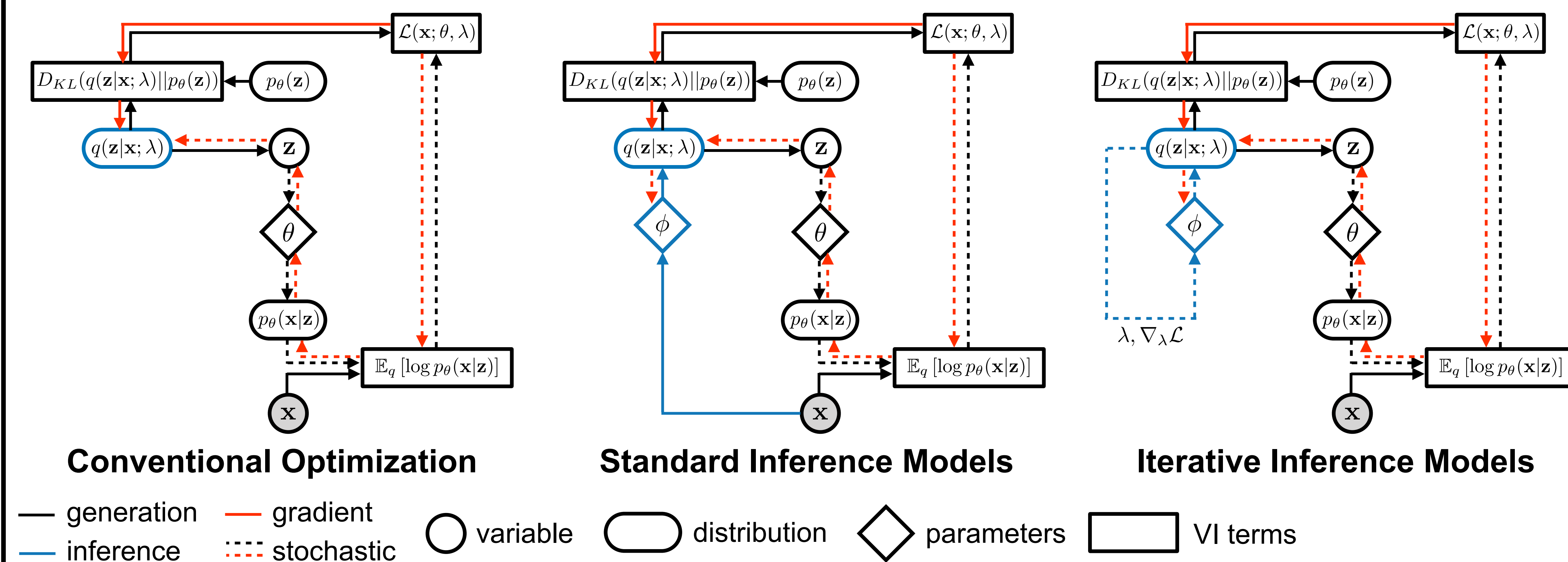
**Standard Inference Models**, (e.g. VAE [3, 4]):

$$\lambda = f_{\phi}(\mathbf{x})$$

**Iterative Inference Models:**

$$\lambda = f_{\phi}(\lambda, \nabla_{\lambda} \mathcal{L})$$

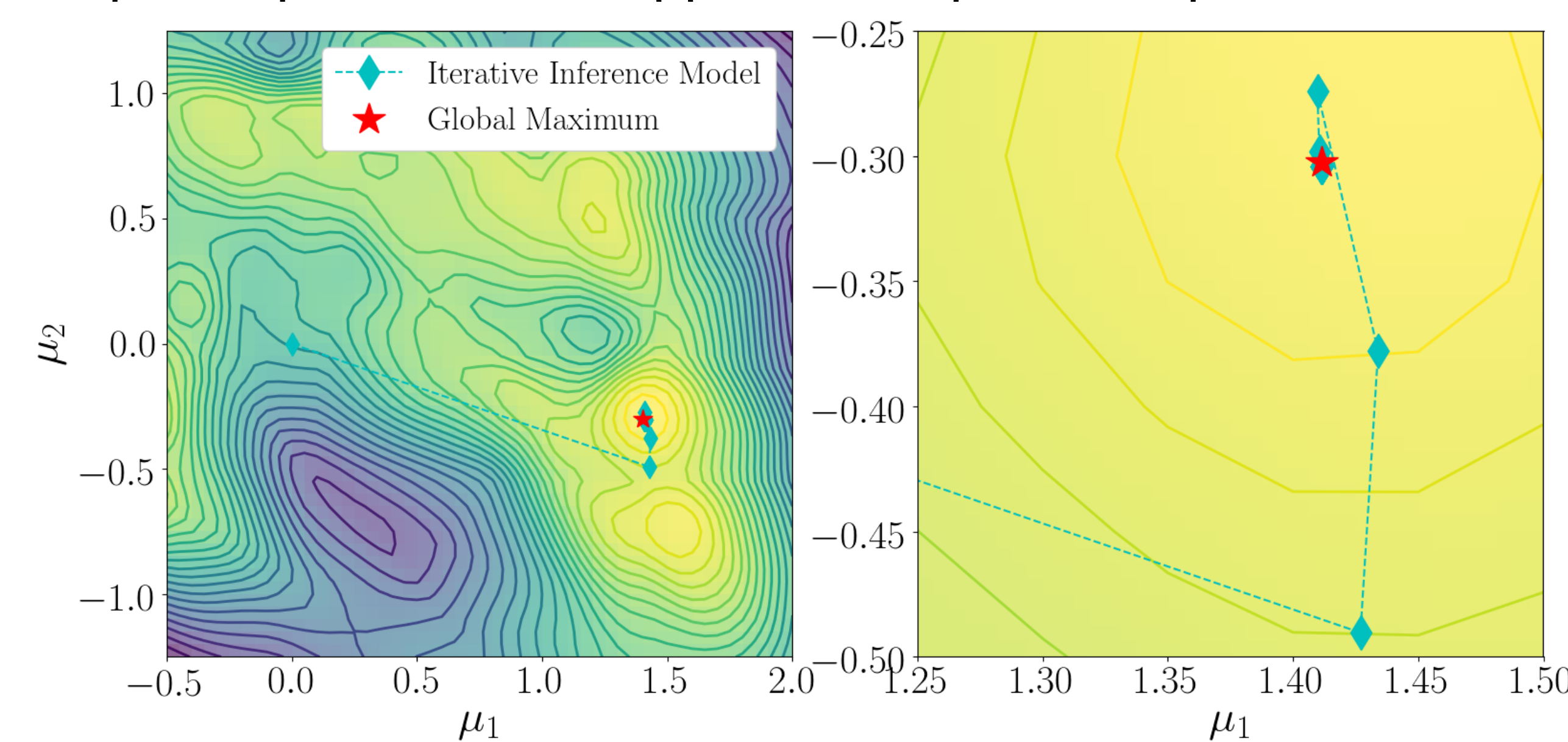
## Computation Graphs



## Results

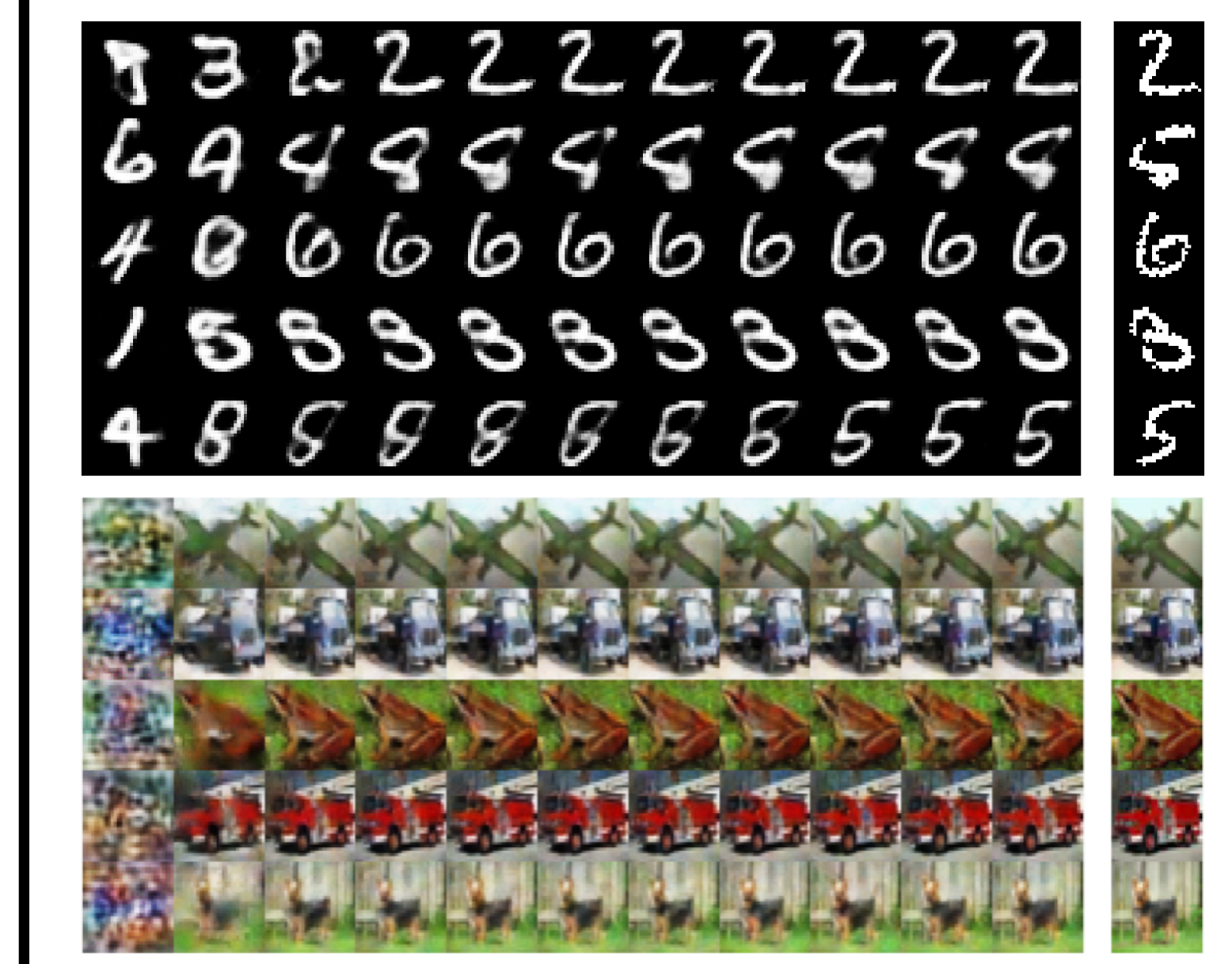
### Visualizing Optimization

Adaptive updates to the approximate posterior parameters.

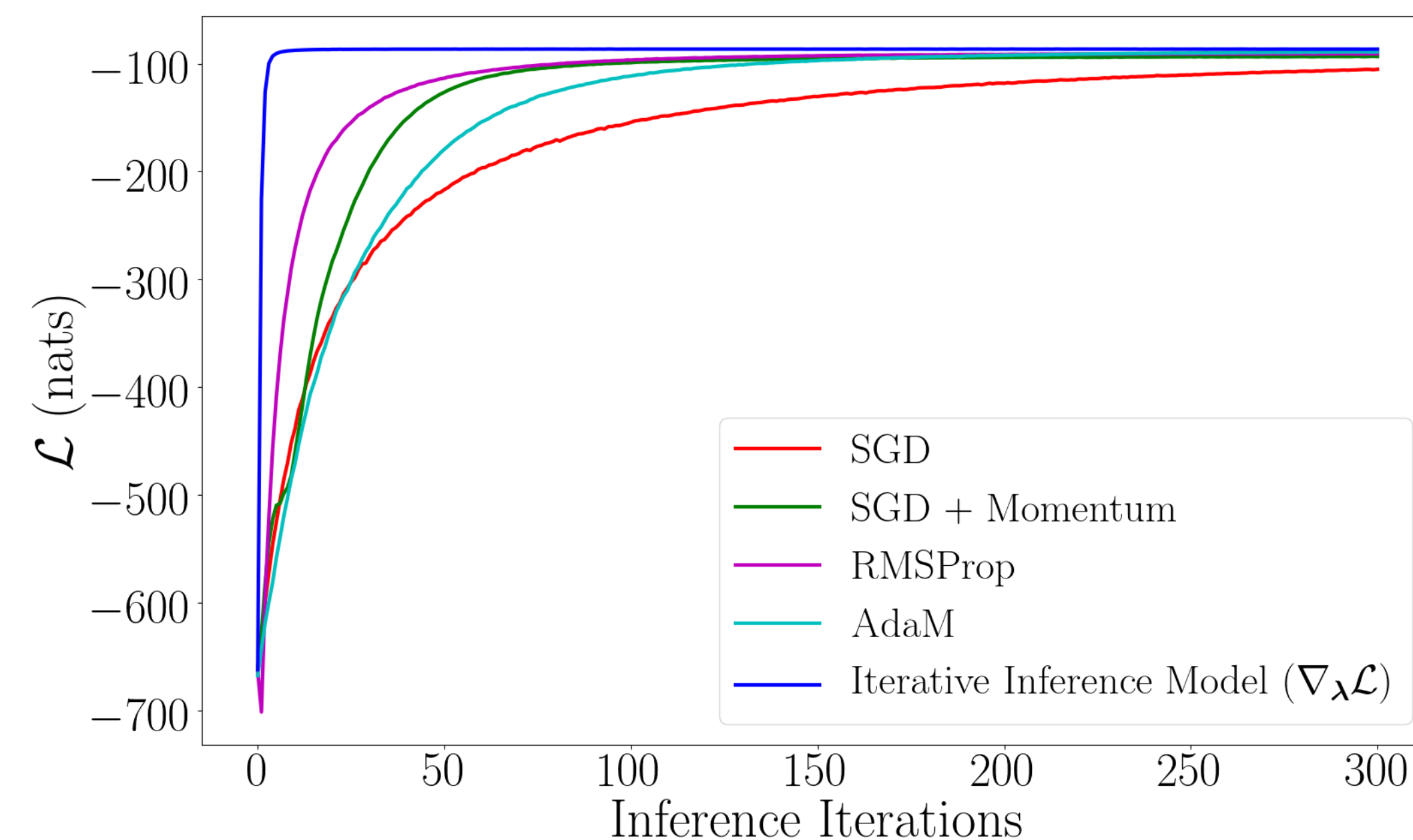


### Reconstructions

Inference Iterations → Data



### Comparing with Conventional Optimization



Iterative inference models outperform conventional optimizers in both speed and performance.

### Comparing with Standard Inference Models

	$-\log p(\mathbf{x})$	Perplexity
<b>MNIST</b>		
Single-Level		
Standard	$84.14 \pm 0.02$	$323 \pm 3$
Iterative	<b><math>83.84 \pm 0.05</math></b>	<b><math>285.0 \pm 0.1</math></b>
Hierarchical		
Standard	$82.63 \pm 0.01$	
Iterative	<b><math>82.457 \pm 0.001</math></b>	
<b>CIFAR-10</b>		
Single-Level		
Standard	$5.823 \pm 0.001$	
Iterative	<b><math>5.64 \pm 0.03</math></b>	
Hierarchical		
Standard	$5.565 \pm 0.002$	
Iterative	<b><math>5.456 \pm 0.005</math></b>	

Iterative inference models outperform comparable standard inference models across data sets and model architectures.

## Discussion

### Encoding Errors

In latent Gaussian models, the gradients for the approximate posterior parameters include Jacobians and errors. E.g.:

$$\nabla_{\mu_q} \mathcal{L} = \mathbf{J}^T \varepsilon_{\mathbf{x}} - \varepsilon_{\mathbf{z}}$$

where

$$\mathbf{J} \equiv \mathbb{E}_{\mathbf{z} \sim q(\mathbf{z}|\mathbf{x})} \left[ \frac{\partial \mu_{\mathbf{x}}}{\partial \mu_q} \right]$$

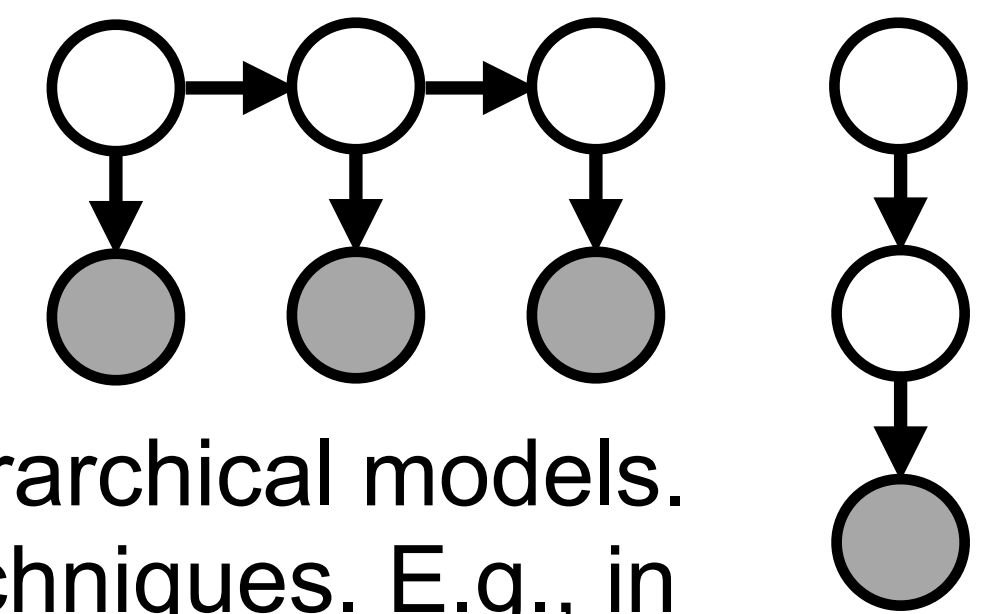
$$\varepsilon_{\mathbf{x}} \equiv \mathbb{E}_{\mathbf{z} \sim q(\mathbf{z}|\mathbf{x})} \left[ \frac{\mathbf{x} - \mu_{\mathbf{x}}}{\sigma_{\mathbf{x}}^2} \right] \quad \varepsilon_{\mathbf{z}} \equiv \mathbb{E}_{\mathbf{z} \sim q(\mathbf{z}|\mathbf{x})} \left[ \frac{\mathbf{z} - \mu_p}{\sigma_p^2} \right]$$

We propose letting the inference model *learn* the Jacobian, encoding the error terms. This allows us to **avoid computing gradients during inference**, and since the errors contain general curvature information, **models of this form can converge to better estimates in fewer iterations.**

### Incorporating Latent Priors

Iterative inference models encode gradients or errors, which **explicitly account for latent priors during optimization**. This is important when these priors vary, as in hierarchical and dynamical models.

Previous works have proposed heuristics to account for these priors, such as top-down inference [5] in hierarchical models. The gradients help to justify these techniques. E.g., in hierarchical models:



$$\nabla_{\mu_q^{\ell}} \mathcal{L} = \mathbf{J}^{\ell T} \varepsilon_{\mathbf{z}}^{\ell-1} - \varepsilon_{\mathbf{z}}^{\ell}$$

where  $\varepsilon_{\mathbf{z}}^{\ell}$  is the “top-down” error from the prior. Without access to these terms, a bottom-up standard inference model must implicitly estimate the prior.

Similar arguments apply to dynamical latent variable models, where iterative inference models can explicitly account for dynamical priors.

1. Radford M Neal and Geoffrey E Hinton. *A view of the em algorithm that justifies incremental, sparse, and other variants*. 1998.
2. Matthew D Hoffman, David M Blei, Chong Wang, and John Paisley. *Stochastic variational inference*. 2013.
3. Diederik P Kingma and Max Welling. *Stochastic gradient vb and the variational auto-encoder*. 2014.
4. Danilo Jimenez Rezende, Shakir Mohamed, and Daan Wierstra. *Stochastic backpropagation and approximate inference in deep generative models*. 2014.
5. Casper Kaae Sønderby, Tapani Raiko, Lars Maaløe, Søren Kaae Sønderby, and Ole Winther. *Ladder variational autoencoders*. 2016.